Surestep[®] Stepping Systems

High-performance microstepping drives with high-torque stepping motors

SureStep stepping systems provide simple and accurate control of position and speed where open-loop control and cost are considerations. Pulses (or "step" and "direction" signals) from the *Direct*LOGIC family of PLCs or other indexers and motion controllers are "translated" by the microstepping drive into precise movement of the stepping motor shaft. The *SureStep* stepping motors use 2-phase technology with 200 full steps per revolution or 1.8° per full step. Older type stepping motor drives, which operate stepping motors in full step mode, can result in stalling or lost motion due to potential problems with low speed mechanical vibration (usually between 100 to 200 RPM). To minimize this vibration

FREE configuration software!

SureStep Pro configuration software is available that makes setting parameters a snap for the advanced drives (STP-DRV-4850 & STP-DRV-80100)! Download free from our website:

http://support.automationdirect.com/products/surestep.html

How fast can my system go?

Maximum Potential Speed Chart						
DirectLOGIC	SureStep [®] Drive Selection (Steps/Rev)					
PLC Pulse Frequency	400 Steps/Rev	1000 Steps/Rev	2000 Steps/Rev	10,000 Steps/Rev		
5,000 Hz	750 rpm	300 rpm	150 rpm	30 rpm		
7,000 Hz	1050 rpm	420 rpm	210 rpm	42 rpm		
10,000 Hz	1500 rpm	600 rpm	300 rpm	60 rpm		
25,000 Hz	3750 rpm	1500 rpm	750 rpm	150 rpm		

*Full step (200 steps/rev) will allow higher top speed. Full stepping, however, can create vibration at low speed. problem, the SureStep microstepping drives use advanced microstepping technology to smooth the motor motion and stepping response. The 4035 has selectable microstep resolutions of 400 (half-step), 1,000 (each full step \div 5 microsteps), 2,000 (\div 10), and 10,000 (\div 50). The advanced drives (STP-DRV-4805, STP-DRV-80100) have software-selectable resolutions ranging from 200 (full step) to 51,200 (\div 256) steps per revolution.

The advanced drives can operate with traditional high-speed inputs, but can also be commanded via 0 - 5V analog input and have an internal indexer that can accomplish point-to-point moves controlled via ASCII communication.

Standards and Agency Approvals

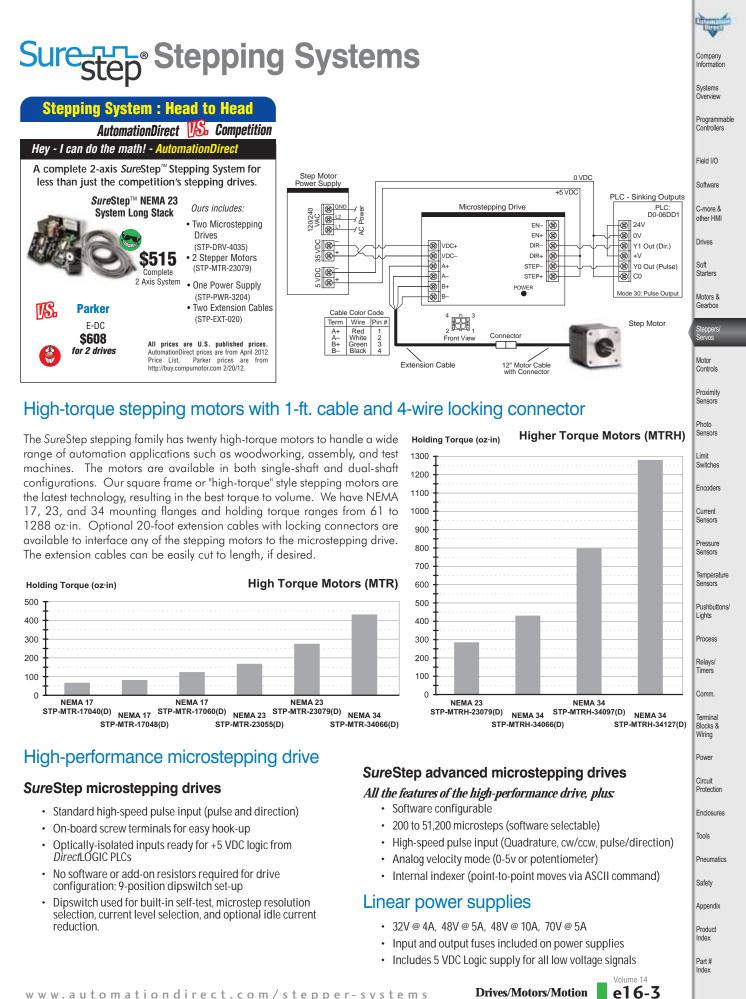
Stepping Motor $RPM = (A \div B) \times (60 \text{ seconds/minute})$

where A = PLC output frequency (pulses per second) B = microstepping resolution selection (steps/revolution)

	RPM =	Steps/Sec A		Steps/Rev B		Sec/Min
Example 1:	1,500 =	10,000	÷	400	х	60
DL06 with 10 kHz Built-in	Pulse Output					
Example 2:	3,750 =	25,000	·	400	Х	60
Hx-CTRIO with 25 kHz Puls	se Output				-	

4 components to make a complete system Choose a drive, motor, motor extension cable and power supply





Surestep[®] Choose your SureStep System

Choose a motor

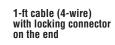
Determine the torque and speed required by your application. Then look at the motor speed-torque curves in this chapter's Technical Info section. Choose a motor that can run your application with plenty of speed and torque reserve (most stepper systems should have a 100% safety margin for torque). NEMA 17, 23 and 34 mounting flanges



Twenty bipolar step motors to cover a wide range of applications

Holding torque ranges from 61 to 1288 oz·in

Single-shaft and Dual-shaft models available



Square frame style produces high torque and achieves best torque to volume ratio

2. Choose a motor extension cable

Our 20-ft motor extension cables have a locking connector that mates up to the motor cable. The extension cables allow you to quickly connect the motor to the drive without having to splice wires or cut any cables. If you chose an STP-MTR-xxxx motor, select an STP-EXT-020 cable. If you chose an STP-MTRH-xxxx motor, select an STP-EXTH-020 cable. (The "H" motors and cable can handle higher motor current)



3 Choose a drive

This chart is a quick selection guide. For a full list of features, check out the Technical Info later in this chapter.

What you need	STP- DRV- 4035	STP- DRV- 4850	STP- DRV- 80100
32V Speed-Torque Curve (from Step 1)	1	\checkmark	\checkmark
48V Speed-Torque Curve (from Step 1)		1	1
70V Speed-Torque Curve (from Step 1)			1
Pulse & Direction Input	\checkmark	\checkmark	 Image: A second s
More than 3.5A/motor phase		\checkmark	\checkmark
More than 5A/motor phase ("H" motors)			√
Internal Indexing (Drive can move from Point A to Point B with a serial communication command)		1	1
Analog Velocity Input		1	1



...in 4 easy steps

4 Choose a power supply

Since all SureStep motors can operate at 32V, 48V, and 70V, the selection of a power supply is dependent on the selected speedtorque curve of the motor and on the selection of drive. Choose a power supply that matches the desired speed-torque curve

Permissible Drive/Power Supply Combinations

Power Supply	STP- PWR- 3204	STP- PWR- 4805	STP- PWR- 4810	STP- PWR- 7005
Drive				
STP-DRV-4035	1			
STP-DRV-4850	1	1	1	
STP-DRV-80100	1	1	1	 Image: A start of the start of

For systems that use multiple drives and only one power supply, please read our SureStep Manual (under "Product Documentation") to properly size multiple systems.

and stays within the voltage limit of the selected drive. Each power supply has incoming AC and outgoing DC fusing. There is also an electronically overload protected 5V supply for all your logic needs.

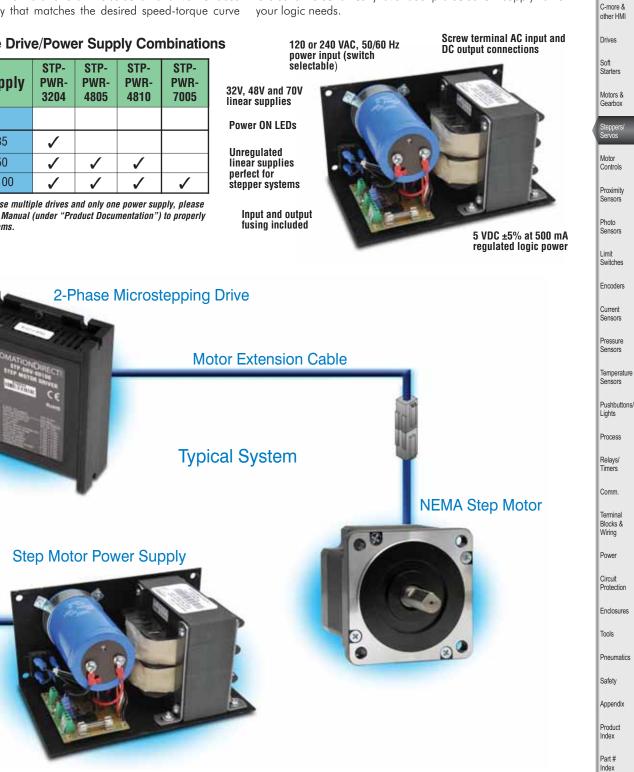
Company Informatio

Systems Overview

Field I/O

Software

Programmable Controllers



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Sure Step Stepping Systems

SureStep[®] System Overview

The SureStep® stepping system series includes:

One DIP-switch configurable microstepping drive

Two software configurable advanced microstepping drives

STP-PWR-3024

V

 $\sqrt{}$

• Twenty step motors (NEMA 17, 23, 34 frame sizes; single shaft & dual shaft)

SureStep Power Supply / Drive Compatibility

Recommended Power Supply⁽¹⁾(2)

STP-PWR-4805

STP-PWR-4810

V

V

1

Four step motor power supplies

Two motor extension cables

Drive(1)(2)

Model #

STP-DRV-4035

STP-DRV-4850

STP-DRV-80100

(40 VDC max input)

(48 VDC max input)





SureStep Step Motor Power Supply

SureStep **Microstepping Drive**

STP-PWR-7005

Νn

No





SureStep **Extension Cable**

SureStep **Connectorized Step Motor**

Standard stepper drive features

- Max 3.5A, 40V
- DIP switch configurable
- Selectable microstepping: x2, x5, x10, x50 steps/revolution
- Self test feature
- Idle current reduction

Advanced stepper drive features

- Max 5A, 48V and max 10A, 80V models available
- Software configurable
- Programmable microsteps
- Internal indexer (via ASCII commands)
- Self test feature
- Idle current reduction
- Anti-resonance
- Torque ripple smoothing
- Step, analog, & serial communication inputs
- Serial communications allow point-to-point positioning

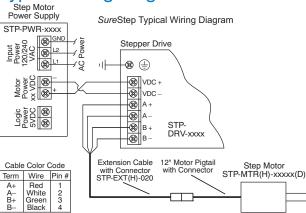
Motor features

- High torque, 2-phase, bipolar, 1.8° per step, 4-lead
- Available in single-shaft and dual-shaft models
- (6) NEMA 17 motors
- (6) NEMA 23 motors
- (8) NEMA 34 motors

Power supply features

- Linear, unregulated DC power supplies
- 120/240 VAC selectable input
- 32V, 48V, 70V DC output models available
- All models have additional 5VDC, 500 mA regulated logic supply
- Fusing included for both incoming AC and outgoing DC
- 5V supply has electronic overload protection

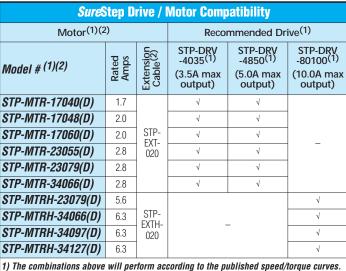
Typical Wiring Diagram



1 (80 VDC max input) 1) Do NOT use a power supply that exceeds the drive's input voltage range. If

using a non-STP linear power supply, ensure that the unloaded voltage does not float above the drive's maximum input range

2) For best performance, use the lowest voltage power supply that supplies the required speed and torque.



However, any STP motor can be used with any STP drive. Using a motor with a current rating higher than the drive's output rating will proportionally limit the motor torque.

2) MTR motors have connectors compatible with the EXT extension cables. MTRH motors have connectors compatible with the EXTH extension cables.

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Surestep® Stepping System Drives

SureStep[®] Microstepping Drives

		Sure Step Series Specifications – Mici	rostepping Drives		
Microstep	oing Drive	STP-DRV-4035	STP-DRV-4850	STP-DRV-80100	
Price		<>	<>	<>	
Drive Type	,	Microstepping drive with pulse input	Advanced microstepping drive (serial communication allows	e with pulse or analog input, serial communication indexing capability)	
Output Cui		selectable from 0.4 to 3.5 A/phase (maximum output power is 140 W)	0.1-5.0 A/phase (in 0.01A increments)	0.1-10.0 A/phase (in 0.01A increments)	
Input Volta (external p	ge /s required)	12-42 VDC (including ripple voltage)	24-48 VDC (nominal) (range: 18-53 VDC)	24-80 VDC (nominal) (range: 18-88 VDC)	
Configurat	ion Method	dip switches	SureStep Pro software (includ	ed)	
Amplifier 1	Туре	MOSFET, dual H-bridge, bipolar chopper	MOSFET, dual H-bridge, 4-qu	adrant	
Current Co	ntrol	3-state PWM 20 kHz	4-state PWM @ 20 kHz		
Protection		n/a	over-voltage, under-voltage, o phase & phase-to-ground), in	ver-temperature, external output faults (phase-to- ter-amplifier shorts	
Recomme Input Fusi		Fuse: 4A fast acting; ADC # ACG4 Fuse Holder: ADC # DN-F6L110	Fuse: 4A 3AG delay (ADC #M Fuse Holder: ADC #DN-F6L1	DL4) Fuse: 6.25A 3AG delay (ADC #MDL6-25) 10 Fuse Holder: ADC #DN-F6L110	
	Input Circuit	Opto-coupler input with 440 Ω resistance (5 to 15 mA input current); Logic Low is input 0.8 VDC or less; Logic High is input 4 VDC or higher.		r less; Logic High is input 4 VDC or higher.	
Input	Step/Pulse	Motor steps on falling edge of pulse and minimum pulse width is 0.5 microseconds (1MHz)	optically isolated, differential, min pulse width = 250 ns max pulse frequency = 2MHz adjustable bandwidth digital n		
Signals	Direction	Needs to change at least 2 microseconds before a step pulse is sent	FUNCTIONS: step & direction tion, jog CW/C	n, CW/CCW step, A/B quadrature, run/stop & direc CW, CW/CCW limits	
	Enable	Logic 1 will disable current to the motor (current is enabled with no hook-up or logic 0)	optically isolated, 5-12V, 680 FUNCTIONS: motor enable, a	$oldsymbol{\Omega};$ ılarm reset, speed select (oscillator mode)	
	Analog	n/a	Range: 0–5 VDC; Resolution	: 12 bit; FUNCTION: speed control	
Output Sig	nal	n/a	optically isolated, 24V, 10mA max; FUNCTIONS: fault, motion, tach		
	ation Interface	n/a	RS-232; RJ11 (6P4C) receptacle		
Non-volati Memory S	torage	n/a	Configurations are saved in F	ASH memory on-board the DSP.	
	Idle Current Reduction	0% or 50% reduction (idle current setting is active if motor is at rest for 1 second or more)	reduction range of 0-90% of r	unning current after delay selectable in ms	
	Microstep Resolution	400 (200x2), 1,000 (200x5), 2,000 (200x10), or 10,000 (200x50) steps/rev	software selectable from 200 t	o 51200 steps/rev in increments of 2 steps/rev	
	Modes of Operation	step & direction	step & direction, CW/CCW, A	/B quadrature, oscillator, joystick, serial commands	
Features	Phase Current Setting	0.4 to 3.5 A/phase with 32 selectable levels	0.1-5.0 A/phase (in 0.01A increments)	0.1-10.0 A/phase (in 0.01A increments)	
	Self Test	uses half-step to rotate 1/2 revolution in each direction at 100 steps/second	checks internal & external pov	ver supply voltages, diagnoses open motor phases	
	Additional Features	n/a	Anti-resonance (Electronic Da Auto setup Microstep emulation Torque ripple smoothing (allows for fine adjustment Waveform (command signal)	of phase in the range 0.25 to 1.5 ros)	
Connector	S	Screw terminal blocks with AWG 18 maximum wire size	Communication: RJ11 (6P40	;); Other: removable screw terminal blocks	
Maximum Humidity		90% no	p non-condensing		
Storage Te	mperature	-20 to 80 °	C [-4 to 176 °F]		
Operating	Temperature	0 to 55 °C [32 to 131 °F] recommended; 70 °C [158 °F] maximum	0-55 °C [32-151 °F]; (mour	nt to suitable heat sink)	
Drive Cool	ing Method	natural convection (mount drive to metal surface to dissipate heat)	natural convection (mount to	suitable heat sink)	
Mounting		(4) #4 screws to mount on wide side; (2) #4 screws to mount on narrow side	#6 mounting screws (mount t	o suitable heat sink)	
Dimension	IS	3.0 x 4.0 x 1.5 inches [76.2 x 101.6 x 38.1 mm]	3.0 x 3.65 x 1.125 inches [76	5.2 x 92.7 x 28.6 mm]	
Weight		9.3 oz. [264 g]	8 oz [227g] (approximate)		
-	provals	CE (complies with EN55011A & EN50082-1 (1992)), RoHS	CE, RoHS		



ZPINK Wiring Solutions

Wiring Solutions using the **ZIP**Link Wiring System

ZIPLinks eliminate the normally tedious process of wiring between devices by utilizing prewired cables and DIN rail mount connector modules. It's as simple as plugging in a cable connector at either end or terminating wires at only one end. Prewired cables keep installation clean and efficient, using half the space at a fraction of the cost of standard terminal blocks. There are several wiring solutions available when using the **ZIP**Link System ranging from

PLC I/O-to-ZIPLink Connector Modules that are ready for field termination, options for connecting to third party devices, GS, DuraPulse and SureServo Drives, and specialty relay, transorb and communications modules. Pre-printed I/O-specific adhesive label strips for quick marking of **ZIP**Link modules are provided with **ZIP**Link cables. See the following solutions to help determine the best **ZIP**Link system for your application.

Solution 1: DirectLOGIC, CLICK and Productivity3000 I/O Modules to ZIPLink Connector Modules

When looking for guick and easy I/O-to-field termination, a ZIPLink connector module used in conjunction with a prewired **ZIP**Link cable, consisting of an I/O terminal block at one end and a multi-pin connector at the other end, is the best solution.



Using the PLC I/O Modules to **ZIP**Link Connector Modules selector tables located in this section, 1. Locate your I/O module/PLC.

- 2. Select a ZIPLink Module.
- 3. Select a corresponding ZIPLink Cable.



Solution 2: DirectLOGIC, CLICK and Productivity3000 I/O Modules to 3rd Party Devices

When wanting to connect I/O to another device within close proximity of the I/O modules, no extra terminal blocks are necessary when using the **ZIP**Link Piqtail Cables. **ZIP**Link Piqtail Cables are prewired to an I/O terminal block with color-coded pigtail with soldered-tip wires on the other end.

Using the I/O Modules to 3rd Party Devices selector tables located in this section,

- 1. Locate your PLC I/O module.
- 2. Select a ZIPLink Pigtail Cable that is compatible with your 3rd party device.



Solution 3: GS Series and DuraPulse Drives **Communication Cables**

Need to communicate via Modbus RTU to a drive or a network of drives?

ZIPLink cables are available in a wide range of configurations for connecting to PLCs and SureServo, SureStep, Stellar Soft Starter and AC drives. Add a ZIPLink communications module to quickly and easily set up a multi-device network.

www.automationdirect.com/drives

Using the Drives Communication selector tables located in this section,

- 1. Locate your Drive and type of communications.
- 2. Select a ZIPLink cable and other associated hardware.



Drives/Motors/Motion

Proximity Sensors Photo Sensors Limit Switches Encoders Current Sensors Pressure Sensors Temperature Sensors Pushbuttons Liahts Process Relays/ Timers Comm Terminal Blocks 8 Wiring Power

Company Information

Systems Overview

Field I/O

Software

C-more &

other HMI

Soft Starters

Motors &

Gearbox

Steppers/

Servos

Motor Controls

Programmable Controllers

Circuit

Pneumatics

Safety

Appendix Product Index Part # Index

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Wiring Solutions

Solution 4: Serial Communications Cables

ZIPLink offers communications cables for use with DirectLOGIC, CLICK, and Productivity3000 CPUs, that can also be used with other communications devices. Connections include a 6-pin RJ12 or 9-pin, 15-pin and 25pin D-sub connectors which can be used in conjunction with the RJ12 or D-Sub Feedthrough modules.

Using the Serial Communications Cables selector table located in this section,

- 1. Locate your connector type
- 2. Select a cable.



Solution 5: Specialty ZIPLink Modules

For additional application solutions, **ZIP**Link modules are available in a variety of configurations including stand-alone relays, 24VDC and 120VAC transorb modules, D-sub and RJ12 feedthrough modules, communication port adapter and distribution modules, and SureServo 50-pin I/O interface connection.

Using the ZIPLink Specialty Modules selector table located in this section,

- 1. Locate the type of application. 2. Select a ZIPLink module.



Solution 6: ZIPLink Connector Modules to 3rd Party **Devices**

If you need a way to connect your device to terminal blocks without all that wiring time, then our pigtail cables with color-coded soldered-tip wires are a good solution. Used in conjunction with any compatible **ZIP**Link Connector Modules, a pigtail cable keeps wiring clean and easy and reduces troubleshooting time.

Using the Universal Connector Modules and Piatail Cables table located in this section,

- 1. Select module type. 2. Select the number of pins.
- 3. Select cable.





Motor Controller Communication

Company Information Systems Overview

Drive / N	lotor Controller		Communication	S		ZIPLink Cable	
Controller	Comm Port Type	Network/Protocol	Connects to	Comm Port Type	Cable (2 meter length)	Cable Connectors	Other Hardware Required
			DL06 PLCs	- Port 2 (HD15)		RJ12 to HD15	-
			D2-260 CPU	- POIL 2 (HD 15)	GS-485HD15-CBL-2		-
iS1	RJ12	RS-485 Modbus RTU	GS-EDRV100	RJ12	GS-EDRV-CBL-2		-
			ZL-CDM-RJ12Xxx*	RJ12	GS-485RJ12-CBL-2	RJ12 to RJ12	-
			FA-ISOCON	5-pin Connector	GS-ISOCON-CBL-2	RJ12 to 5-pin plug	-
			CLICK PLCs	— Port 2 (RJ12)			_
			DL05 PLCs				_
			DL06 PLCs				
		RS-232 Modbus RTU	D2-250-1 CPU	Port 2 (HD15)	GS-RJ12-CBL-2	RJ12 to RJ12	FA-15HD
			D2-260 CPU				
S2	RJ12		D4-450 CPU	Port 3 (25-pin)			FA-CABKIT
			P3-550 CPU	Port 2 (RJ12)			-
			DL06 PLCs	- Port 2 (HD15)	GS-485HD15-CBL-2	RJ12 to HD15	-
			D2-260 CPU		GS-4000010-CDL-2		-
		RS-485 Modbus RTU	GS-EDRV100	RJ12	GS-EDRV-CBL-2	- RJ12 to RJ12	-
			ZL-CDM-RJ12Xxx*	RJ12	GS-485RJ12-CBL-2		-
			FA-ISOCON	5-pin Connector	GS-ISOCON-CBL-2	RJ12 to 5-pin plug	-
			DL06 PLCs	- Port 2 (HD15)	GS-485HD15-CBL-2	RJ12 to HD15	-
uraPulse		RS-485 Modbus RTU	D2-260 CPU				-
iS3)	RJ12		GS-EDRV100	RJ12	GS-EDRV-CBL-2	RJ12 to RJ12	-
,			ZL-CDM-RJ12Xxx*	RJ12	GS-485RJ12-CBL-2		-
			FA-ISOCON	5-pin Connector	GS-ISOCON-CBL-2	RJ12 to 5-pin plug	-
allar			DL06 PLCs	_			
ellar oft Starter)	RJ45**	RS-485 Modbus RTU	D2-250-1 CPU	Port 2 (HD15) SR44-485HD15-CBL-2	RJ45 to HD15	SR44-RS485**	
R44 Series			D2-260 CPU				
			ZL-CDM-RJ12Xxx*	RJ12	SR44-485RJ45-CBL-2	RJ45 to RJ12	
			CLICK PLCs	- Port 2 (RJ12)		6-pin IEEE to RJ12	-
			DL05 PLCs	. ,	_		-
			DL06 PLCs	-			
		RS-232 Modbus RTU RS-485 Modbus RTU	D2-250-1 CPU	Port 2 (HD15)	SVC-232RJ12-CBL-2		FA-15HD
			D2-260 CPU				
ureServo	IEEE1394 (CN3)		D4-450 CPU	Port 3 (25-pin)			FA-CABKIT
			P3-550 CPU	Port 2 (RJ12)	SVC-485HD15-CBL-2	6-pin IEEE to HD15	-
			DL06 PLCs	- Port 2 (HD15)			-
			D2-260 CPU				-
			ZL-CDM-RJ12Xxx*	RJ12	SVC-485RJ12-CBL-2	6-pin IEEE to RJ12	-
			USB-485M	RJ45	SVC-485CFG-CBL-2	6-pin IEEE to RJ45	-
	RJ12	RS-232 ASCII	DL06 PLCs			HD15-pin to RJ12 RJ12 to RJ12	-
			D2-250-1 CPU	Port 2 (HD15) ST	STP-232HD15-CBL-2		-
ureStep			D2-260 CPU (Port2)				-
			DL05 PLCs	- RJ12	STP-232RJ12-CBL-2		-
			CLICK PLCs				-

Drives/Motors/Motion

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