Considerations for Choosing a Controller Use the worksheet on the following pages as a checklist of the things to consider when determining

Use the worksheet on the following pages as a checklist of the things to consider when determining programmable controller requirements. It lists the most important areas to consider when choosing a system, and provides space for recording determinations of your system needs.

Consideration	Information	ı to Record	Why this is important
1. Proposed System	New system	Existing system	Determine whether your system is new or existing: Will your system be installed from scratch or are there existing products already installed? The rest of your system will need to be compatible with new components. Why this is important: Certain controller products may not be compatible with others. Making sure your existing products are compatible with any new products you are researching will save you time and money. Check appropriate entry.
2. Environmental Issues	Codes/environmental issues to consider	No codes or environmental issues to con- sider	Consider any environmental issues that will affect your application (temperature, dust, vibration, codes specific to your facility, etc.). Why this is important: Certain environments may affect the opera- tion of a controller. For example, typical controllers have an oper- ating temperature of 0-55 degrees Celsius (32-130 degrees F). If your application will include any extreme environmental condi- tions, or you have specific codes at your facility that must be met, you will need to either research products that meet those specifi- cations or design the installation to meet requirements. Check appropriate entry.
3. Discrete Devices	Total inputs: AC DC	Total outputs: AC DC	Determine how many discrete devices your system will have. Which types (AC, DC, etc.) are needed? Why this is important: The number and type of devices your system will include is directly linked to the amount of I/O that will be necessary for your system. You will need to choose a controller that supports your I/O count requirements and has modules that support your signal types.Enter quantities and type based on corre- sponding field devices.
4. Analog Devices	Total inputs: Voltage Current Thermo RTD	Total outputs: Voltage Current	Determine how many analog devices your system will have. Which types (voltage, current, temperature, etc.) are needed? Why this is important: The number and type of devices your system will include is directly linked to the amount of I/O that will be necessary for your system. You will need to choose a controller that supports your I/O count requirements and has modules that support your signal types. Enter quantities and type based on corre- sponding field devices.
5. Specialty Modules or Features (application- specific)	High speed course Positioning Servo/stepper BASIC program Real-time clock Others (list)	nming	Determine whether your system will require any specialty features: Will your application require high-speed counting or positioning? What about a real-time clock or other specialty feature? Why this is important: Specialty functions are not necessarily avail- able in a controller CPU or in standard I/O modules. Understanding the special functions your system may perform will help you determine whether or not you will need to purchase addi- tional specialty modules. Check all features required.

Table continued on the following page

Considerations for Choosing a Controller



Company Information Systems

Consideration	Information to Record	Why this is important	Programmable Controllers
6. CPU Required	Hardware requirements:	Determine the type of CPU you will need: How much memory will your system require? How many devices will your system have (determines data memory)? How large is your program, and what types of instructions will your	Field I/O Software
	K program memory required (estimated)	program include (determines program memory)? How fast a scan time do you need? Why this is important: Data memory refers to the amount of memory needed	C-more & other HMI Drives
	K data memory required (estimated)	for dynamic data manipulation and storage in the system. For example, counter and timer instructions typically use data memory to store setpoints, current values, and other internal flags. If the application requires historical data retention, such as measured device values over a long period of time,	Soft Starters Motors &
	Fast scan time required?	the size of the data tables required may determine the CPU model you choose. Program memory is the amount of memory needed to store the	Gearbox Steppers/
	Battery backup required?	sequence of program instructions that have been selected to perform the application. Each type of instruction requires a specific amount of program memory, typically defined in a programming manual. Applications that are	Servos Motor Controls
	Software/special function requirements:	basically sequential in nature can rely on the I/O device rule of thumb to esti- mate program memory (five words of memory for each I/O device); complex applications will be more difficult to judge.	Proximity Sensors
	PID	If scan time is important in your application, consider the CPU processor speed as well as instruction execution speed. Some CPUs are faster at boolean logic but slower with data handling instructions.	Photo Sensors
	Floating Point Math	If special functions such as PID are required, the CPU you select may make those functions easier to perform.	Switches
	Others (see Programming section below)	For program memory required, follow this rule of thumb: 5 words of pro- gram memory for each discrete device and 25 words for each analog device. Check or calculate all requirements that apply.	Current Sensors
		Determine where your I/O will be located: Will your system require only local I/O, or both local and remote I/O locations?	Pressure Sensors
	Local only Specific remote I/O protocol required? Which one?	Why this is important: If subsystems will be needed at long distances from the CPU, you will need a controller that supports remote I/O. You will also have to determine if the remote distances and speeds supported will be adequate for your application. Serial and Ethernet-based I/O hardware are two typical choices available for most systems. This I/O may also be referred to as distributed I/O, and may require a particular protocol, such as Modbus.	Temperature Sensors Pushbuttons/ Lights Process Relays/ Timers
		Enter number of physical locations needed, and if/what specific protocol may be required.	Comm.
9. Programming	Ethernet PLC to PLC	Determine your communication requirements: Will your system be communicating to other networks, systems or field devices?	Terminal Blocks & Wiring
	Modbus RTU ASCII (interface to serial devices) Other	Why this is important: Communication ports (other than the programming port) are not always included with a controller. Knowing your system communication requirements will help you choose a CPU that supports your communication requirements, or additional communication modules	Power Circuit Protection
	PID loops	if necessary. Check any/all communications functions required. Determine your programming requirements: Does your application require	Enclosures Tools
	Floating number of loops needed	only traditional programming instructions, or are special instructions neces- sary? Why this is important: Certain controllers may not support every type of instruc-	Pneumatics Appendix
	Subroutines	tion. You will need to choose a model that supports all instructions that you may need for a specific application. For example, built-in PID functions are	Product
	Drum sequencer Direct interrupts Others (list)	much easier to use than writing your own code to perform closed-loop process control. Typical instructions such as timers, counters, etc. are available in most controllers; note any other special instructions required here. Check	Index Part # Index
		any/all programming functions required.	

eCS-5